## Towards a Theory of Tracing for Functional Programs based on Graph Rewriting

Olaf Chitil and Yong Luo

 $\label{eq:University} \begin{array}{l} \mbox{University of Kent, UK} \\ \mbox{Supported by EPSRC grant EP/C516605/1} \end{array}$ 

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A Theory of Tracing

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## Tracing Functional Programs

#### Why Tracing?

- Locate a fault (wrong output, run-time error, non-termination).
- Comprehend a program.

Two-Phase Tracing: A trace as data structure



- Liberates from time arrow of computation.
- Enables views based on different execution models. (small-step, big-step, interpreter with environment, denotational)
- Enables compositional views.

# The Haskell Tracer Hat (www.haskell.org/hat)

Multi-View Tracer



• Trace = Augmented Redex Trail (ART); distilled as unified trace.

Aim: A theoretical model of the ART.

## The Programming Language

#### Launchbury's and related semantics

- Subset of  $\lambda$ -calculus plus case for matching.
- Any program can be translated into this core calculus.

#### For tracing

- Close relationship between trace and original program essential.
- Language has most frequently used features:
  - named functions
  - pattern matching

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```
⇒ Higher-order term rewriting system
```

```
sort [] = []
```

```
sort (x:xs) = insert x (sort xs)
```

```
insert x [] = [x]
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```
insert x (y:ys) = if x > y then y: (insert x ys) else x:ys
```

## Graph Rewriting I



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- Create new nodes for right-hand-side.
- Nodes of subexpressions are shared.

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- Create new nodes for right-hand-side.
- Nodes of subexpressions are shared.
- Some old nodes become garbage.

## Graph Rewriting II



sort [] = []
sort (x:xs) = insert x (sort xs)
insert x [] = [x]
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## Graph Rewriting II



sort [] = []
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• Application node of redex replaced by new node.

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Image: A mathematical states and a mathem

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### The Trace



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#### The Node Naming Scheme



#### Aim

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#### Solution

- standard representation with node describing path from root
- path at creation time (sharing later)
- path independent of evaluation order

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## The Node Naming Scheme II



- Reduction edge implicitly given through existence of node.
- Node encodes parent; parent = top node of redex causing its creation:

```
parent(nt) = n

parent(nl) = parent(n)

parent(nr) = parent(n)

parent(\epsilon) = undefined
```

Easy to identify right-hand-side of rule: same parent.

An ART G for start term M, program P and semantics  $\cong$  is a partial function from nodes to term constructors,  $G : n \mapsto T$ , defined by

- The unshared graph representation of *M* is an ART.
- If G is an ART and
  - L = R an equation of the program P,
  - $\sigma$  a substitution replacing the variables of the equation by nodes not ending in t,
  - n ∈ dom(G) represents Lσ,
  - $nt \notin dom(G)$ ,
  - G' is the unshared graph representation of  $R\sigma$ ,
  - $L\sigma \cong R\sigma$

then  $G \cup G'$  is an ART.

Evaluation order is not fixed.

## A Reduction Step

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- closed (no dangling nodes)
- odomain prefix-closed
- no term constructor contains node ending in t
- only a node ending in t can be an indirection
- if  $n \in dom(G)$ , then G(n) = n m
- if  $nr \in dom(G)$ , then G(n) = m nr
- if  $nt \in dom(G)$ , then n and nt represent a reduction step
- acyclic
- subcommutative
- . . .

Give non-inductive definition of ART based on properties?

```
sort "sort" = "os"? n
insert 's' "o" = "os"? v
sort "ort" = "o"? n
insert 'o' "r" = "o"? n
Bug identified:
  "Insert.hs":8-9:
  insert x [] = [x]
  insert x (y:ys) = if x > y then y:(insert x ys) else x:ys
```

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### The ART and the Evaluation Dependency Tree



## Conclusions

#### Summary

- simple model amenable to proof
- contains a wealth of information about computation
- models real-world trace of Haskell tracer Hat
- proved correctness of algorithmic debugging



- still play with definitions
- drop non-needed nodes from ART
- model run-time error with error value
- allow local function definitions ( $\Rightarrow$  free variables)
- share reductions of constants ( $\Rightarrow$  cycles in graph)