WADS 2009

On the Design of Adaptive-and-dependable Systems Lessons learned and experiences at the University of Antwerp

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Agenda



- Adaptive-and-Dependable Software Systems
 - Where
 - What, Why, How
- How: @ UA
 - Memory-based metaphor
- Conclusions

Introduction – ADSS: Where



- UA, University of Antwerp, Belgium
 - Approximately 10.000 students, third largest in Flanders
- Quite young university
 - 2003, merge of three smaller universities
 - roots go back to 1852



- Seven Faculties, including Sciences
 - Dept. of Computer Science and Mathematics

$UA \Rightarrow PATS$



TO:



Welcome

The Performance Analysis of Telecommunication Systems (PATS) research group is part of the Department of Mathematics and Computer Science 妃 of the University of Antwerp 妃. The group was founded in 1995. PATS performs basic, applied and contract research related to the performance analysis of telecommunication systems and the impact of performance on the architecture and the design of these systems.

The PATS research group is one of the groups that are involved in the Interdisciplinary Institute for Broadband Technology (IBBT) @ which was founded by the Flemish government on March 19th of 2004.

(Read more ...)

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$\mathsf{UA} \Rightarrow \mathsf{PATS} \Rightarrow \mathsf{ADSS}$



Research line: Adaptive-and-Dependable Software Systems

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Adaptive-and-Dependable Systems – a research line of the <u>PATS group</u> at the <u>University of Antwerp</u>, Belgium.

Often the systems our societies depend upon are built in such a way as to result too inflexible and intolerant to changes. The deployment of such systems in environments where change is the rule rather than the exception leads to situations where quality-of-service and qualityof-experience are strongly and negatively affected. As a result, there is an urgent need to investigate structuring techniques, architectures, algorithms, tools, and paradigms for the expression and the management of adaptive-and-dependable software systems, i.e., software, devices, and services that are built so as to sustain an agreed-upon quality-of-service and quality-of-experience despite the occurrence of potentially significant and sudden changes or failures in their infrastructure and surrounding environments. This need is the core business of this research line

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ADSS: What?



- OK, but what are « Adaptive-and-dependable sw systems »?
- Let me answer by recalling first what Real-Time Software (RTS) is:
 - "Real-time software is software that interacts with the world on the world's schedule, not the software's.
 - It senses the world and responds to changes in the world when those changes occur."

ADSS: What?



- RTS = an entity that executes in a «virtual world,» but monitors and synchronizes with the physical world – what time is concerned
- RTS = organized and built so as to keep track of *the timing* of physical world's events and do as much as possible to avoid *timing failures*
- An ADSS is something similar

ADSS: What?



- ADSS may be considered as a generalisation of RTS:
- It is organized and built so as to keep track of (the timing of) physical world's events and do as much as possible to avoid (timing) failures
 - QoS failures, QoE failures
- Both RTS and ADSS: Open world assumption

ADSS: What



 Thus ADSS is "software that is built so as to sustain an agreed-upon quality-of-service and quality-of-experience despite the occurrence of potentially significant and sudden changes or failures in their infrastructure and surrounding environments."



• ADSS: Why

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- Worst-case analyses do not pay off anymore!
 - Truly effective approaches forbid upper bounds; instead, they require a precise characterization of the allocation of resources over time
 - Unwanted emergent behaviors can only be avoided if the systems are built with "a finer-grain control of the redundancy degree" (Esposito and Cotroneo, 2009) and of the other available resources



- Worst-case analyses do not pay off anymore (cont.'ed)
 - WCA = no optimal way to choose the amount of redundancy
 - « What is the *minimal* redundancy matching the *current environmental conditions* (threats / disturbances...)? »
 - → Close world solutions are inefficient



- Hidden intelligence syndrome!
 - A dependable system is built atop several assumptions or hypotheses
 - Explicit or implicit ones
 - Those are «contracts» that must not be ignored, lest dependencies turn into failures



- Hidden intelligence syndrome (cont.'ed)
 - A few examples
 - «HW includes a MMU» ⇒ memory errors may be detected
 - «Memory technology is SDRAM» ⇒ memory fails through single-event effects (instead of bitflips)
 - «The platform includes hardware interlocks» ⇒ any malfunction shuts down the system
 - «Reasonable amount of redundancy is 3 replicas» ⇒ single failure assumption



- Hidden intelligence syndrome (cont.'ed)
 - HIS calls for ways to express & evaluate assumptions such as those
 - The fault model, the system model, the platform dependencies should be expressable and verifiable
 - Software reuse, porting, re-deployment, call for re-evaluation and re-organization
 - → Necessary services of any truly dependable architecture: ADSS!







- Indeed we're living in «highly fluid environments»!
 - "Large, networked and evolving systems either fixed or mobile, with demanding requirements driven by their application domain"
 - "Complex, ever changing, ubiquitous and pervasive systems" (Simoncini, 2009)
- Those are the systems that suffer most from the Horning syndrome
 - "What is the most often overlooked risk in software engineering?

That the environment will do something the designer never anticipated" [J. Horning]



- Ultra large-scale systems!
 - A shift from "small, monolithic and vertical architectures [..] toward large highly modular, autonomous, heterogeneous and integrated systems of systems" (Esposito & Cotroneo, 2009)
 - Large scale Complex Critical Infrastructures : based on best-effort WANs, though both reliable and timely!
 - Require adaptive-and-dependable sw architectures



- The only possible assumption is the open-world one
- "The assumption that the system software architecture is known and fixed at an early stage of system development does not apply anymore. On the contrary the ubiquitous scenario promotes the view that systems can be dynamically composed out of available components"
- "In this setting the software architecture can only be dynamically induced" (Inverardi, today!)



• ADSS: How

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ADSS: How?



- Not a single research direction
- ADSS@UA/PATS :
 - ACCADA, A Continuous Context-Aware Deployment and Adaptation framework on top of OSGi (Ning Gui)
 - SoA+AOP framework (OSGi/Equinox) (Hong Sun)
 - Apache Muse/Axis2 framework (Jonas Buys)
 - Reflective C
 - Adaptive data structures...

Reflective C



- Reflective & refractive variables (RR vars)
- Redundant variables
- Meta variables



- Main idea: memory accesses as a metaphor for detecting changes and reacting from changes
- An abstraction to realize open-world software
- RR vars = volatile variables whose identifier links them with an external device, e.g. a sensor, or an RFID, or an actuator



- Reflective variables: memory cells get asynchronously updated by probes
 - Probes: service threads interfacing external devices
- Refractive variables: Write accesses trigger a request to perform some action
 - E.g. set frame dropping policy of a media player or amount of redundancy to be employed
 - Write accesses *refract* (that is, get redirected) onto corresponding external devices



- An hello world application can be built via program crearr
- This creates a "hello world" code that uses reflective variable cpu:

crearr -o example -rr cpu

🖏 ~/sources/RRvar-v4.0	📬 ~/sources/RRvar-v4.0	
\$ crearr -o example -rr cpu The following files have been created: [vg The following file has been updated: examp	r] and Makefile <mark>Vincenz@PCINF55 ~/sources/RRvar-v4.0</mark> le.c	
Vincens@PCINF55 ~/sources/RRvar-v4.0 \$ cat example.c /* File example.c		_ //
* created/modified on Sat Dec 13 * by crearr for Sat Dec 13 23:35:	crearr -o example -rr cpu	
*/		
<pre>#include <stdio.h> #include <sys types.h=""> #include <sys stat.h=""> #include <unistd.h> #include <string.h> #include <assert.h></assert.h></string.h></unistd.h></sys></sys></stdio.h></pre>		
<pre>#include "reflection.h" #include "rcode.h"</pre>		
extern char verbose;		
<pre>char *server_address = "localhost";</pre>		
<pre>#include "rrvars_init.h"</pre>		
<pre>void PrintCpu(void) { printf("cpu == %d\n"</pre>	, cpu); }	
int main (int argc, char *argv[])		
۲ RR_VARS		
RR_VAR_CPU		
<pre>rrparse("(cpu>0);", PrintCpu);</pre>		
<pre>while (1) sleep(2); }</pre>		
<pre>#include "rrvars_end.c"</pre>		
<pre>/* End of file example.c */</pre>		6
Vincenz@PCINF55 ~/sources/RRvar-v4.0 \$]		0







- Callbacks through function rrparse.
- When a guard is evaluated as true, the callback is executed
- Default guard is trivial: amount of CPU > 0
- Default callback: print current amount of CPU
 - "Similar" behavior:

while (1) { if (cpu > 0) Callback(); }.

Another example:





rxvt	×□	rxvt
oash–3.2\$ mplayer –vo gl ~/sources/RRvar–v4.0/clip.mp4 MPlayer dev–SVN–r23011–3.4.4 (C) 2000–2007 MPlayer Team CPU: Intel(R) Pentium(R) M processor 2.13GHz (Family: 6, Model: 13, Stepping: 8) CPUflags: MMX: 1 MMX2: 1 3DNow: 0 3DNow2: 0 SSE: 1 SSE2: 1 Compiled for x86 CPU with extensions: MMX MMX2 SSE SSE2	▲ bash-3.2\$ crearr -o exa The following files hav The following file has bash-3.2\$ g gcc -fmessage-length=60 bash-3.2\$ r	e been created: [vgr].
laying /home/Vincenz/Sources/RRvar–v4.0/clip.mp4. SO: File Type Major Brand: ISO/IEC 14496–1 (MPEG–4 system) v1 uicktime/MOV file format detected. IDEO: [mp4v] 400x224 Obpp 25.000 fps 0.0 kbps (0.0 kbyte/s) g]] using extended formats. Use –vo g]:nomanyfmts if playback fails.	Mplayer server: startin (GET,cpu), (PUSH,O), (> Mplayer server: waiting cpu == 24 cpu == 100	
pening video decoder: [ffmpeg] FFmpeg's libavcodec codec family elected video codec: [ffmdjuy] vfm: [ffmeg (FFmeg MPEC-4)	cpu == 99 cpu == 99 cpu == 100	
ACC [dsourd] #4100"z 2% stole (2 bytes per sample) ACC [dsourd] #4100"z 3% stole (2 bytes per sample) ACC [dsourd] #4100	Cpu == 100 Cpu == 99 Mplayer server: from 12 Mplayer server: mplayer cpu == 99 cpu == 100 cpu == 100 cpu == 100 cpu == 100 cpu == 100 cpu == 99 cpu == 99 cpu == 99 cpu == 100	
🖼 MPlayer - Media player for Win32		

Rai





	rxvt	×		rxvt
MPlayer deu-SVN-r230 CPU: Intel(R) Pentiu CPUflags: MMX: 1 MM	o gl ~/sources/RRvar-v4.0/clip.mp4)11-3.4.4 (C) 2000-2007 MPlayer Team)m(R) M processor 2.13CHz (Family: 6, Model: 13, Stepping: 8) 1X2: 1 3DNow: 0 3DNow2: 0 SSE: 1 SSE2: 1) with extensions: MMX MMX2 SSE SSE2		The The basi gcc	h-3.2\$ crearr –o example –rr cpu mplayer –c following files have been created: [vgr]. following file has been updated: example.c h-3.2\$ g -fmessage-length=60 –g –o example example.c interp.tab.c lex.y h-3.2\$ r
ISO: File Type Major Quicktime/MOV file f VIDEO: [mp4v] 400x [g1] using extended	nz/sources/RRvar-v4.0/clip.mp4. • Brand: ISO/IEC 14496-1 (MPEG-4 system) v1 format detected. (224 Obpp 25.000 fps 0.0 kbps (0.0 kbyte/s) formats. Use -vo gl:nomanyfmts if playback fails.		Mpla (GE ⁺ Mpla Cpu Cpu	n=3.cp r ayer server: starting T,cpu), (PUSH,O), (>,(null)), ayer server: waiting for data on port UDP 1500 == 24 == 100 == 99
Opening video decode Selected video codec	r: [ffmpeg] FFmpeg's libavcodec codec family :: [ffodivx] vfm: ffmpeg (FFmpeg MPEG-4)		сри сри сри	== 99 == 100 == 100
AUDIO: 44100 Hz, 2 c Selected audio codec	:r: [faad] AAC (MPEG2/4 Advanced Audio Coding) :h, s16le, 79.8 kbit/5.66% (ratio: 9981->176400) :: [faad] afm: faad (FAAD AAC (MPEG-2/MPEG-4 Audio) decoder)		сри сри сри	== 99 == 100 == 100 == 100
AO: [dsound] 44100Hz Environment variable mplayer::udpopen: se sending 4 Starting playback VDec: vo config requ Could not find match Opening video filter VDec: using Planar Y Movie-Aspect is 1.79	: 2ch s16le (2 bytes per sample) : RRVAR_CLIENT undefined, setting to localhost :nding data to 'PCINF55' (IP : 127.0.0.1) :est - 400 x 224 (preferred colorspace: Planar YV12) ing colorspace - retrying with -vf scale		cpu Mpl. cpu cpu cpu cpu cpu cpu cpu cpu	== 100 == 99 ayer server: from 127.0.0.1:UDP1891 : 4 ayer server: mplayer started == 99 == 100 == 100 == 100 == 100 == 100 == 99 == 99
<pre>vo: [g]] 400x224 => exit_sighandler(2) sending 5 sending 2</pre>			cpu cpu cpu Mpla Mpla cpu Mpla	== 99 == 99 == 99 aver server: mplayer caught an exception aver server: mplayer caught signal 2 == 99 aver server: from 127.0.0.1:UDP1891 : 1 aver server: mplayer caught signal 2 == 99 aver server: mplayer stopped
			сри сри сри	== 99 == 100 == 99 == 99 == 99

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if (verified) Callback(³⁴

	rxvt		x1
ISO: File Type M Quicktime/MOV fi VIDEO: [mp4v] [g]] using exter	ncenz/sources/RRvar–v4.O/clip.mp4. Major Brand: ISO/IEC 14496–1 (MPEG–4 system) v1 le format detected. 400x224 Obpp 25.000 fps 0.0 kbps (0.0 kbyte/s) Med formats. Use –vo gl:nomanyfmts if playback fails.	▲ Mplayer server: starting (GET,cpu), (PUSH,O), (>,(null)), Mplayer server: waiting for data cpu == 24 cpu == 100 cpu == 100	on port UDP 1500
Opening video de Selected video d	coder: [ffmpeg] FFmpeg's libavcodec codec family codec: [ffodivx] vfm: ffmpeg (FFmpeg MPEG-4)	cpu == 99 cpu == 100 cpu == 99 cpu == 100	
AUDIO: 44100 Hz, Selected audio o	coder: [faad] AAC (MPEG2/4 Advanced Audio Coding) 2 ch, s16le, 79.8 kbit/5.66% (ratio: 9981->176400) codec: [faad] afm: faad (FAAD AAC (MPEG-2/MPEG-4 Audio) decoder)		
	OOHz 2ch s16le (2 bytes per sample)	cpu == 100 cpu == 99 cpu == 100	
Environ mplayer sending Startin = = = VDec. v	System is too	cpu == 100 Mplayer server: from 127.0.0.1:UU Mplayer server: mplayer started cpu == 100 cpu == 99	DP1996 : 4
Cou7d n	DW	cpu == 99 cpu == 99 cpu == 100 cpu == 100 cpu == 100	
\$0: [g]] 400×224		cpu == 99 cpu == 100 cpu == 99 cpu == 100	
	Your system is too SLOW to play this! **** ********************************	cpu == 99 cpu == 100 cpu == 100 cpu == 100	
- Most common; b - Try -ao sdl - Experiment v - Slow video out	roken/buggy _audio_ driver or use the OSS emulation of ALSA. with different values for -autosync, 30 is a good start. put	cpu == 100 cpu == 100 cpu == 100 cpu == 100 cpu == 100	
- STOW CPU	ent -vo driver (-vo help for a list) or try -framedrop!	cpu == 100 cpu == 100	
	<pre>i play a big DVD/DivX on a slow CPU! Try some of the lavdopts, mpeg -lavdopts lowres=1:fast:skiploopfilter=all.</pre>	cpu == 100 Mplayer server: from 127.0.0.1:UC Mplayer server: mplayer slowed do	
– Try various – Slow media (NF	combinations of -nobps -ni -forceidx -mc O. S/SMB mounts, DVD, VCD etc)	cpu == 100 cpu == 100	
	-cache to play a non-interleaved AVI file?	cpu == 100 cpu == 99 cpu == 100	
	 n/video.html for tuning/speedup tips. helps you, read DOCS/HTML/en/bugreports.html.	Mplayer server: from 127.0.0.1:UD Mplayer server: mplayer caught ar	PP1996 : 5 n exception
sending 2		Mplayer server: mplayer caught st cpu == 100	ignal 2
exit_sighandler(sending 5 sending 2	(2)	Mplayer server: from 127.0.0.1:UC Mplayer server: mplayer stopped cpu == 100	P1996 : ↓ ↓ ↓
		cpu == 100 cpu == 100	
	ited by signal 2 in module: decode_audio	cpu == 100 cpu == 99	35
bash-3, 25 bash-3, 25		🔽 bash-3.25 🛛	



void SystemIsSlow(void) {

printf("Mplayer reports 'System too slow to
play clip' and CPU is above threshold:\n");
// drop frames more easily
mplayer = HARDFRAMEDROP; }

rrparse("(cpu>98)&&(mplayer==2);",
 SystemIsSlow);

- - -
Other RR vars



- int watchdog
 - Watchdog states if negative, and the amount of received heartbeats otherwise
- int bandwidth
 - Estimated bandwidth available b/w two TCP endpoints
- int linkbeacons[«MAC address»]
 - Number of beacons received during the current observation period in an ad hoc network
- int linkrates[«MAC address»]
 - Estimated bandwidth available between two nodes in an ad hoc network



- « Worst case analysis do not pay off anymore... »
 - Common approach to choosing how much redundancy to employ: close-world assumption: "Fixed, reasonable choice, dependent on the context" ⇒
 - 1.overshooting: over-dimensioning the design with respect to the actual threat being experienced
 - 2.undershooting: underestimating the threat in view of an economy of resources



- Adaptively redundant data structures
 - Variables whose contents get replicated several times so as to protect them from memory faults
 - Writing to a redundant variable = writing to *n* replicas, located somewhere and according to some strategy
 - Reading from a redundant variable = reading the n cells, performing majority voting
 - The result of this process is monitored by a RR var probe, which measures the amount of votes that differ from the majority
 - A measure of the disturbance in the surrounding environment



- *n* is *n(t)*
- Under normal situation, *n*=3
 - The system triplicates the memory cells of redundant variables
 - This corresponds to tolerating up to one memory fault
- Under more critical situations, the amount of redundancy is adjusted
- The adjustment logic should tune in the ideal degree of redundancy with respect to the current disturbances





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- As already explained, RR vars have:
 - public side, where the adaptation and error recovery logics are specified by the user in a familiar form
 - private side, separated but not hidden, where the probing and actuation logics are defined.
- The logic in the private side can be indeed monitored and controlled by means of meta RR vars, i.e., variables reflecting / refracting on the state of the RR var system



- Information produced by error detectors is not discarded but fed into a fault identification mechanism (α-count)
- The current value of this mechanism is available to the user in the form of meta RR var alphacount[i]
 - i identifies the error detector



 This allows to set up assertions on the validity of the fault model, e.g.

```
void AssumptionMismatch(void) {
    printf("Wrong fault model assumption
        caught\n");
}
```

```
rrparse("(alphacount[1]>3.0);",
AssumptionMismatch);
// 3.0 = Alpha-count threshold
```



- A scenario involving a watchdog (left-hand window) and a watched task (right-hand).
- The watched task is repeatedly interrupted and restarted, so as to emulate the effect of some permanent fault.
- As a consequence, the watchdog "fires" and updates an α -count variable.
- The value of the α-count variable increases until it reaches a threshold (3.0)
- \rightarrow Fault is labeled as permanent-or-intermittent.



	rxvt	
bash-3.2\$./w		bash-3.2\$ watched localhost
watchdog == -3 (Watchdog has started)	>	InitLibrary sender: sending (
∦atchdog 1 has been started.		sending OK
Watchdog 1 activated		→^C
watchdog == -2 (Watchdog is active)	/	bash-3.2\$ watched localhost
watchdog == -2 (Watchdog is active)		InitLibrary_sender: sending (
Watchdog l fired		sending OK
watchdog == -1 (Watchdog has fired)		
alphacount = 1.000000, fault (if any) i	s transient	<pre>bash-3.2\$ watched localhost</pre>
Restarting watchdog		<pre>InitLibrary_sender: sending (</pre>
Watchdog 1 has been restarted.		sending OK
Watchdog 1 activated		
watchdog == -2 (Watchdog is active)		<pre>bash-3.2\$ watched localhost</pre>
alphacount = 1.000000, fault (if any) i	ls transient	<pre>InitLibrary_sender: sending @</pre>
Watchdog l fired		sending OK
watchdog == -1 (Watchdog has fired)		
alphacount = 2.000000, fault (if any) i	s transient	<pre>bash-3.2\$ watched localhost</pre>
Restarting watchdog		InitLibrary_sender: sending (
Watchdog l has been restarted.		sending OK
Watchdog l activated		
watchdog == -2 (Watchdog is active)		<pre>bash-3.2\$ watched localhost</pre>
alphacount = 2.000000, fault (if any) i	ls transient	<pre>InitLibrary_sender: sending @</pre>
Watchdog l fired		sending OK
watchdog == -l (Watchdog has fired)		
alphacount = 3.000000, fault (if any) i	s permanent or intermittent.	
Restarting watchdog		InitLibrary_sender: sending
Watchdog 1 has been restarted.		sending OK
Watchdog 1 activated		
<pre>watchdog == -2 (Watchdog is active)</pre>		<pre>bash-3.2\$ watched localhost</pre>
alphacount = 3.000000, fault (if any) i	s permanent or intermittent	
Watchdog l fired		sending OK



- Worst-case analyses do not pay off anymore
 - → Redundant vars as optimal way to choose the amount of redundancy
- Horning syndrome
 - → RR vars to express and realize open-world systems
- Hidden intelligence syndrome
 - → Meta RR vars to set up assertions on the validity of the fault / system models and platform



- An excerpt of our current research directions in Antwerp
- Future steps: other mechanisms to allow more systematically the design time hypotheses about system and environment to be expressed and asserted
- Ultimate challenge: intelligent management of the dependability strategies



Thank you for your attention! Questions?

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