

μ Cell - Interdisciplinary Research in Modelling and Simulation of Cell Spatial Behaviour (Shorter Version)

Dominic Orchard, Jonathan Gover, Lee Lewis Herrington,
James Lohr, Duncan Stead, Cathy Young, Sara Kalvala

May 18, 2009

Abstract

A central aim of systems biology is the strengthening of quantitative and qualitative knowledge of biological systems by studying the interactions between components and processes that lead to emerging properties and behaviours. Systems biology proliferated over the latter half of the 20th century with the aid of technological advances and subsequent interdisciplinary research between natural scientists, computer scientists, and mathematicians. In this paper we present μ Cell, an interdisciplinary research project undertaken by undergraduates at the University of Warwick, seeking to aid systems biology intuition. The project delivered a modelling and simulation tool for multi-cellular environments aimed at simulating higher-level cellular behaviours based on the interoperation of metabolic dynamics models of cell biochemistry and procedural models of cell structures, such as flagella. Based on these interoperated models μ Cell is able to simulate spatial properties and behaviours of cells, such as chemotaxis. This paper introduces μ Cell, gives a case study model and simulation, and discusses the pedagogical outcomes of the project for the students.

Note on shorter version

This is a slightly shorter version of a paper published in the Reinvention Journal, April 2009. This version excludes discussion of the pedagogical outcomes of the work, its context within the interdisciplinary research of Warwick University, and discussion of the development methodologies adopted in developing μ Cell. A couple of short elaborations appear in sections 2.2.2 and 5 in sans font. Any citations or quotations should be taken from the **full** online version of this paper. The published article can be found online at <http://www2.warwick.ac.uk/go/reinventionjournal/issues/volume2issue1/orchard>.

1 Introduction

Studying components and processes of cell independently from other components and processes often fails to expose the full spectrum of a cell's properties and behaviour. The study of emergent behaviours and properties at the cellular and organismal level requires an understanding of the dynamic interactions and causal relationships between individual lower-level processes within a cell, and between cells. In the last decade, interdisciplinary research between natural scientists, computer scientists, and mathematicians has greatly improved understanding through computational analyses, modelling, and simulation.

We present here the μ Cell modelling and simulation tool for multicellular environments where spatial behaviours can be simulated from models of biochemical signalling pathways interoperated with abstract *procedural* models of cell components, such as flagella. The models are procedural in the sense that they describe the operations of a component in the form of a program procedure. This model-interoperation approach contrasts with the approach of deriving spatial simulations purely from abstract statistical models, such as in the Cellular Potts Model [6]. The aim of μ Cell is to improve understanding of the mediating role of cell biochemistry to spatial behaviour. This paper discusses the modelling and simulation of flagella-based *chemotaxis* in *E. coli* bacteria as an example usage of μ Cell.

μ Cell is the result of interdisciplinary research undertaken by a group of six final year undergraduate students in the Department of Computer Science at the University of Warwick during 2007/2008 for the fulfilment of the final-year group project requirement for the MEng Computer Science course¹.

This paper is structured as follows. Section 2 describes the materials and methods, including the computer science methods and software development techniques employed in developing μ Cell, the key components of the μ Cell software, and the example models used to simulate chemotaxis. Section 3 describes the results of chemotaxis simulations in μ Cell and the learning outcomes of the project. Section 4 describes related work, followed by a discussion of further work and conclusions.

2 Materials and Methods

2.1 μ Cell overview

The μ Cell software comprises three main components: the *editor*, *simulator*, and *analyser*. Included in this section are screenshots of μ Cell. The software can be downloaded from the μ Cell Wiki¹ along with the μ Cell manual.

¹<http://github.com/dorchard/mucell/wikis/>

2.1.1 Editor

The *editor* provides an interface for the construction and configuration of a cell models and experiments. An experiment consists of a set of cell models, called *cell definitions*, and a set of simulations. Simulations consist of an environment, a configuration of cells instantiated from cell models, and various parameters governing data capture for analysis. Cell models are defined in terms of signalling pathways that model the biochemical reactions within a cell, and in terms of a set of predefined cell component models. These predefined procedural cell component models may have some parameters but are atomic: the user cannot deconstruct them or modify them directly.

Signalling pathways are constructed in the cell definition editor by drawing graphs of reactions and molecules (called *species*) (Figure 1) where reaction rates are described in mass action form. Pathways can be imported and exported using the Systems Biology Markup Language (SBML) [8] standard. The procedural cell component models can be integrated into a signalling pathway as nodes in the pathway graph where input and output points of the components are linked to species. Thus the procedural cell component models can be placed in signalling pathway and can affect changes or be affected. Procedural models linked into a pathway cannot be exported to the SBML format as they are not part of the SBML standard.

Simulations are constructed by configuration of an initial state, including the size and shape of the environment (box, tube, petri-dish, or sphere/orb Figure 2), spatial arrangement of cells, staining of cells (as is standard practice in real-world experimental biology) (Figure 3), concentration gradients (Figure 4), and other global parameters regarding the environment or simulation. For statistical analysis and data logging *time-series* can be defined in terms of formulae associated with the simulation to be calculated at user-defined time intervals (Figure 5).

2.1.2 Simulator

The *simulator* runs a simulation from a given experiment. Cells are instantiated from cell definitions (models) each having their own set of internal chemical concentrations used in the signalling pathway, spatial properties (such as velocity and orientation), and parameterised components belonging to the cell as described by the procedural models.

Signalling pathways are simulated using finite difference methods such as Runge-Kutta and Euler methods for the approximation of differential equations. Approximations are computed iteratively using the time step interval specified in the simulation configuration.

All formulae ascribed to the simulation, time-series formulae and reaction rates, are parsed from their user-specified form into an abstract syntax tree. The abstract syntax tree is “folded” into a C# function during initialization

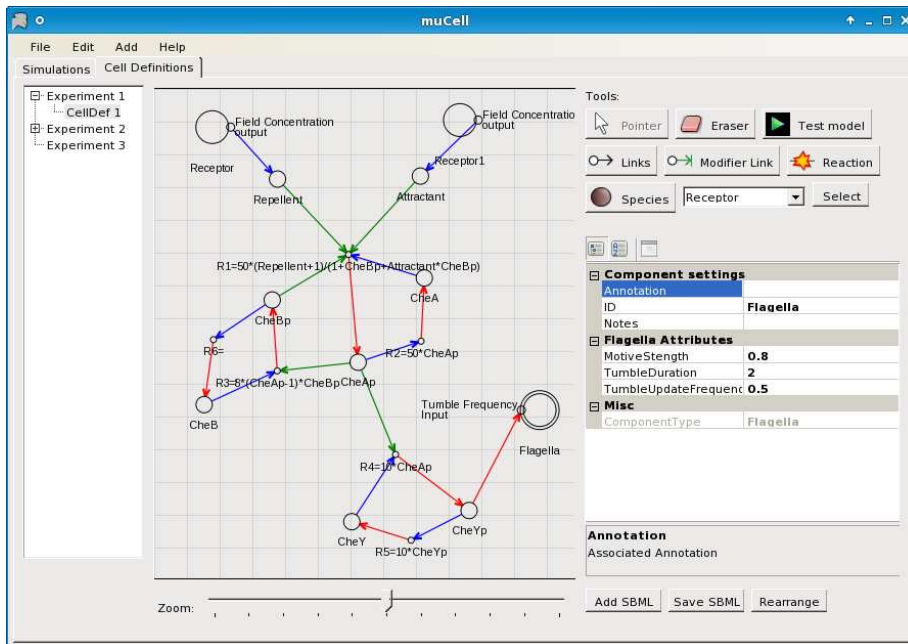


Figure 1: μ Cell cell model editor - Editing an imported SBML model.

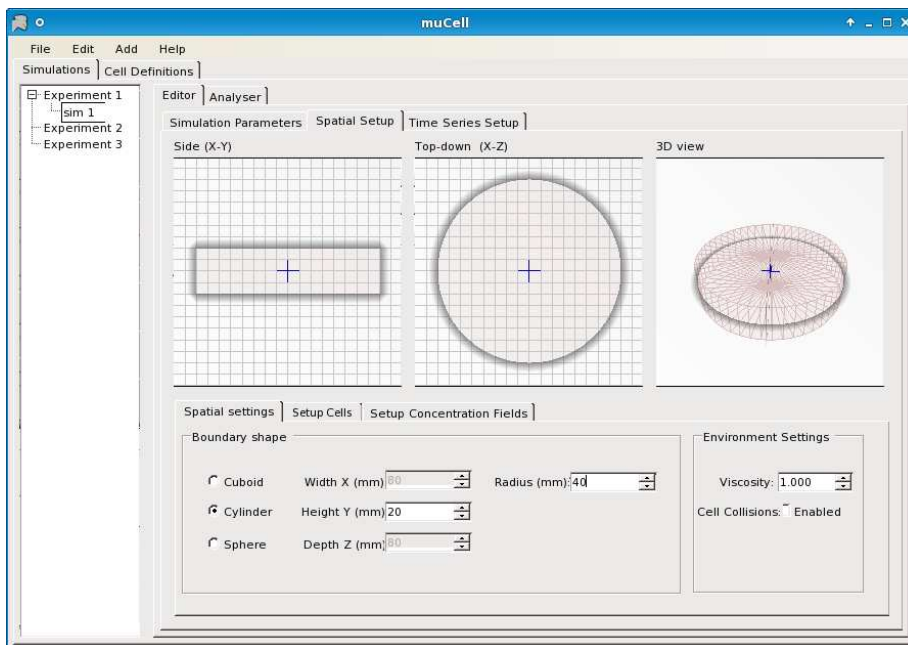


Figure 2: μ Cell spatial environment editor - Defining the size and shape of the simulation environment.

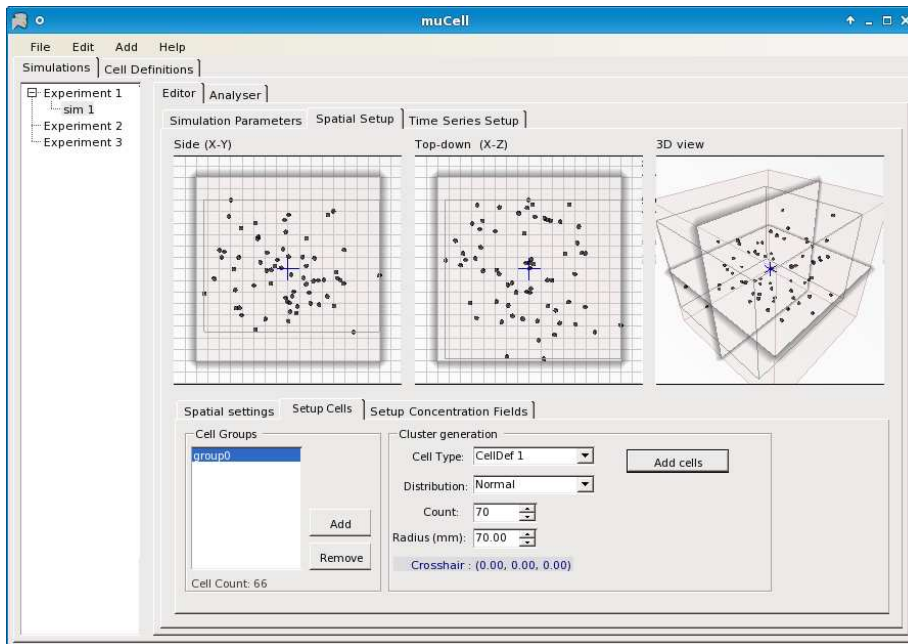


Figure 3: μ Cell spatial editor for cells - Defining initial cell placement.

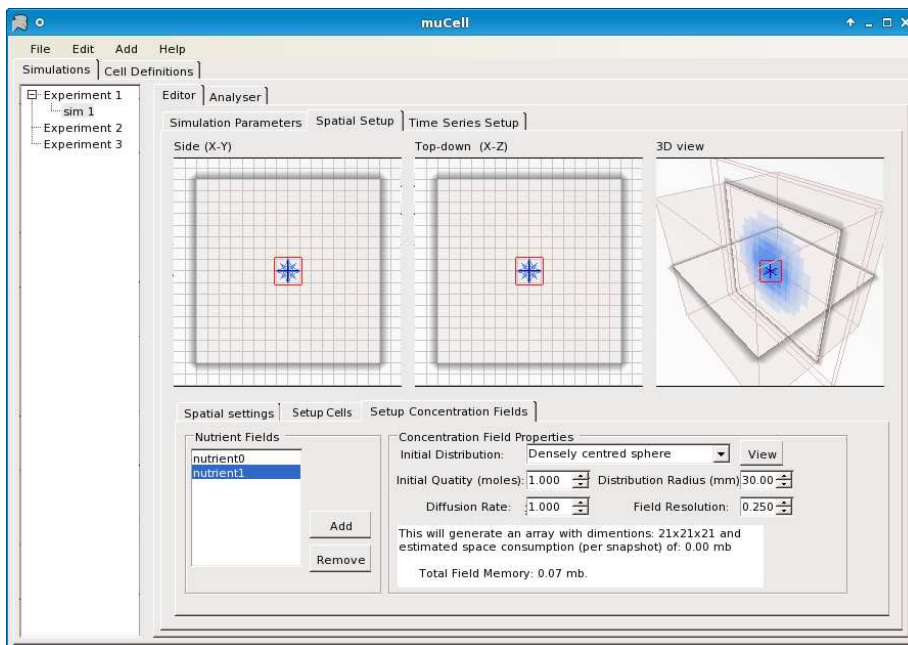


Figure 4: μ Cell concentration gradients editor - Defining concentration fields and diffusion.

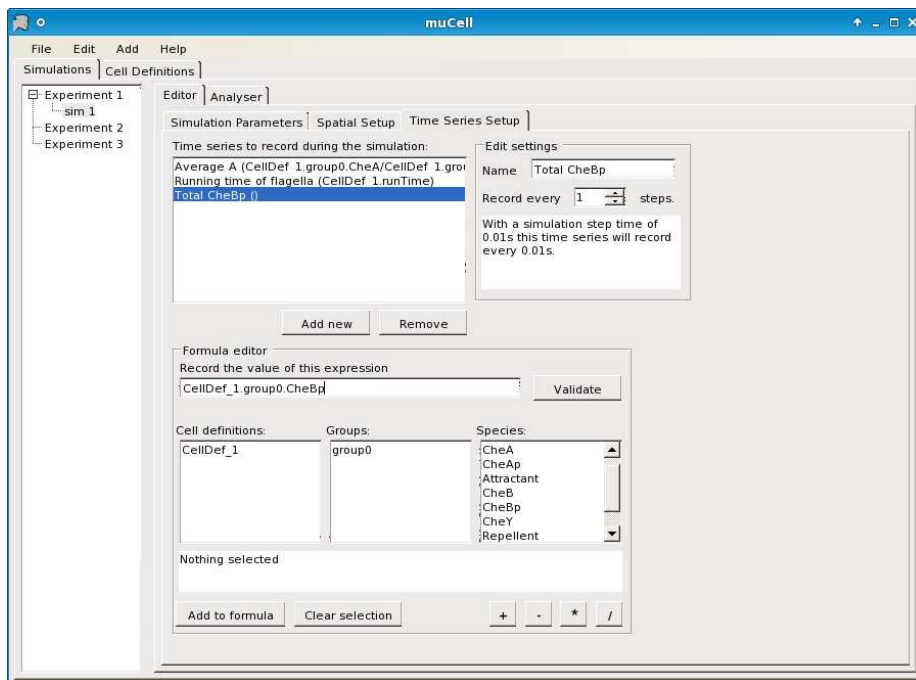


Figure 5: μ Cell time series editor - Defining formulae for time-series data to be generated by a simulation.

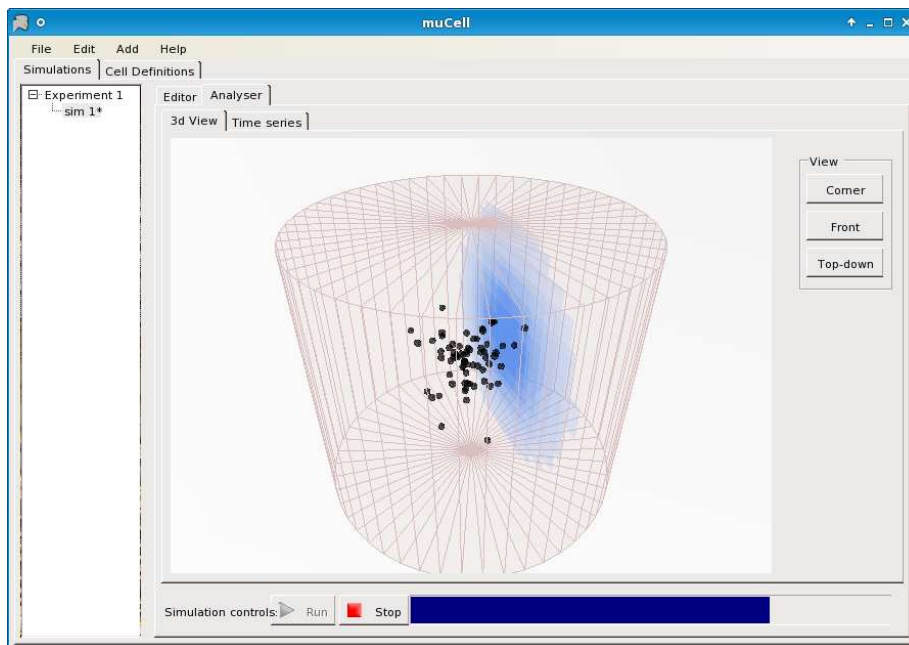


Figure 6: μ Cell Analyster - The 3D simulation environment shows the spatial position of cells. A 2D planar view of the concentration scans over the environment.

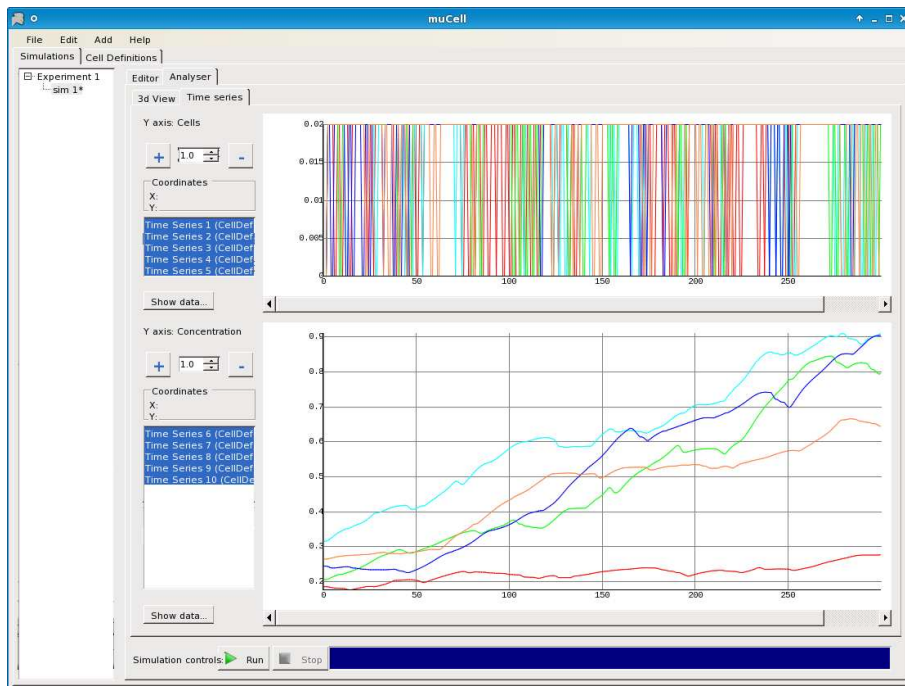


Figure 7: μ Cell Analyser - Plots showing concentration of attractant during chemotaxis and run duration for 5 sampled cells.

of the simulation using C#'s functional programming concepts. The folded function provides an efficient representation for calculating formulae at each iteration of the simulation.

Whilst pathways are simulated via approximations of differential equations, the procedural models of cell components are hard-coded as C# classes with “step” methods run at each iteration of the simulation which may interact with local chemical constituents, either within the cell, or in the environment at the current spatial position. Procedural models can affect other parameters of the cell such as spatial properties.

An additional spatial simulator, which resembles a classic physics simulator, maintains cell locations, collisions, and boundaries within a continuous Cartesian space, as opposed to quantising locations into a grid as in cellular automata. In the current simulator, cells reaching a boundary are simply deflected without loss of energy. By default the cells are represented as points in the space but can be given a size and mass via the “cell body” component for simulating collisions.

2.1.3 Analyser

The *analyser* provides an interface for viewing data collected during and after a simulation, and provides feedback on simulation progress. The anal-

yser provides a 3D representation of the spatial environment and the cells within it (Figure 6). Concentration gradients are shown via a 2D planar slice that moves through the environment showing a coloured representation of the concentration in that plane where a lighter colouring corresponds to a low molar concentration and a darker colouring corresponds to a high concentration.

The analyser also provides access to time-series data generated during simulation in the form of plots (Figure 7). The raw numerical data for the plots can be viewed and exported to CSV format for importing into other tools, spreadsheets, or analysis tools. We developed a few small external tools for analysis of flagella run and tumble duration data, written in Haskell, which will later be incorporated into μ Cell.

2.2 Modelling and Simulating Chemotaxis

The following section explains the features of μ Cell that allow the modelling and simulation of more complex behaviours in cells that bring together signalling pathways and cell components. In particular, we explain how μ Cell can be used for the modelling and simulation of flagella-based chemotaxis in *E. coli* towards an arbitrary attractant by a biased random walk.

In the simulation, the random walk effect of the chemotaxis is induced by the interoperation of signalling pathway models with procedural models of receptor and flagella, and simulations of concentration gradients. The simulated random walk behaviour of chemotaxis is *not* encoded explicitly in any of the models but is an emerging behaviour of the system.

2.2.1 Introduction to Chemotaxis

Chemotaxis is a form of cell motility that is promoted by chemical concentrations in an environment. Chemicals promoting chemotaxis may act as attractants or repellents, affecting the *average* directional movement of a cell. Remarkably, chemotaxis allows a cell to move up an attractant concentration gradient (or down a repellent gradient) despite the fact that a cell is too small to measure a concentration gradient in space. This cell overcomes its size limitation by measuring the concentration gradient temporally [15].

There are many modes of transport for a cell performing chemotaxis. Here we focus on chemotaxis facilitated by flagella. Motile force is provided by a bundle of flagella which rotate either clockwise or anticlockwise. Anticlockwise rotation of the flagella produces a force directed towards the centre of the cell, propelling the cell forwards in a straight line called a *run*. Clockwise rotation of the flagella produces a force directed away from the centre of the cell resulting in the cell *tumbling*² randomly on the spot.

²Some older literature refers to this action as *twiddling*.

The cell alternates between the two phases of either tumbling or running with some *tumble probability* affecting the tumble frequency. A temporal increase in attractant, or decrease in repellent, reduces the flagella tumble probability, thus reducing the tumble frequency (on average), resulting in longer runs when moving up a concentration gradient of attractant or down a concentration gradient of repellent. Conversely a decrease in attractant, or an increase in repellent, increases the tumble probability, thus runs become shorter [3]. Thus, the cell performs a random walk with a bias towards a high concentration of attractants and a low concentration of repellents.

The cell adapts its internal biochemistry to the new level of attractants in the environment as it moves in a straight line so that the cell converges to a stable tumble frequency in both extremely high and extremely low levels of concentration. In effect, the tumble frequency is independent of the magnitude of concentration; a temporal gradient of concentration is required to stimulate the cell to alter its tumble frequency.

The link between chemotaxis and flagellar motion has been the subject of much interest over the last 30 years, and *E. coli* has been a very commonly used model for the study of this mechanism. The signalling pathway for sensing is well understood [12], however “much remains to be understood” about the flagellar motor [16]. The extensive knowledge of *E. coli* motility has been derived from wet experiments and biophysical modelling; a spatial simulation linking the flagellar motor’s effect with the signalling pathways could be a useful addition to the arsenal of tools available to bacteriologists.

Our chemotaxis model is derived from a simple metabolic network of just three molecules and procedural models of receptors and flagella. The procedural model for a receptor is extremely simple in μ Cell, taking a sample of a specified molecule’s concentration at the cell’s current spatial position. The model of a receptor thus resembles the very entry point of a molecule into a cell – there are no methylation bindings for controlling reception in the model. Concentration gradients and diffusion are simulated in μ Cell by a lower resolution approximation of the spatial environment. We describe the method for simulating concentrations first, followed by the signalling pathway used in the chemotaxis model, and finally the flagella bundle model.

2.2.2 Simulating concentration gradients and diffusion

μ Cell discretises the concentration gradients in the spatial environment by approximating the environment as a set of discrete cubes of uniform volume that describe a uniform molar quantity of some molecule. The size of the cubes, hence the resolution of the approximation, can be configured in the simulation parameters to suit available system resources; higher precision approximations result in greater memory usage. A mapping from points in the continuous spatial environment to corresponding discrete cubes returns the concentration of a molecule at a point in the environment. Diffusion is

simulated across each face of a cube at a constant diffusion rate specified by the user.

For a cube q_i and an adjacent cube q_j the rate of diffusion from q_i to q_j is defined as:

$$\frac{d(q_i)}{dt} = (q_j - q_i) \times C_A \times k \quad (1)$$

where C_A is the face area of the cubes and k is a diffusion rate constant specified by the user.

The initial distribution of a concentration can be specified either uniformly or as a densely centred sphere that approximates an initial diffusion from a fixed point. An initial quantity is set by the user specifying the concentration of the molecule that will be added to the environment.

The discretisation process poses a problem for chemotaxis as it introduces sudden, sharp changes in concentration between cubes and uniform concentrations inside a cube. Chemotaxis relies on continuous changes in the concentration gradient. The discretisation problem is overcome by interpolation using Gaussian weighting (see Appendix A).

2.2.3 Signalling pathway for Chemotaxis

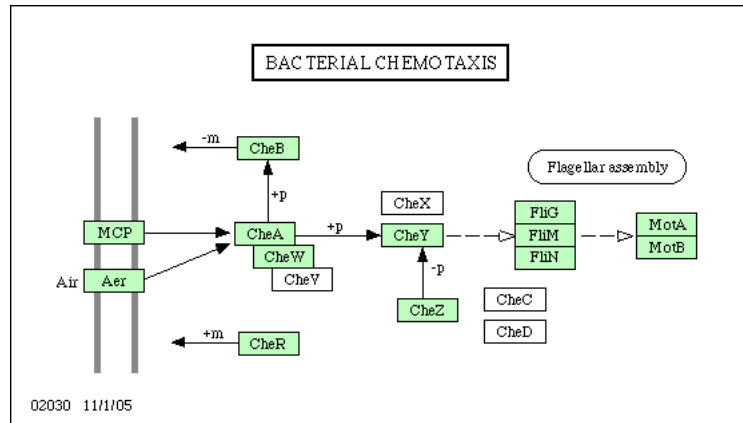


Figure 8: Pathway for bacterial chemotaxis in *E. Coli* taken from the KEGG database. [9, 10]

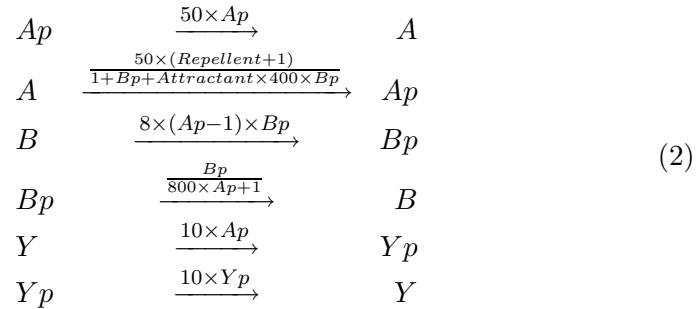
The metabolic pathway for the chemotaxis model is derived from the known chemotaxis pathway of *E. coli* with some simplifications; Figure 8 shows the metabolic pathway. We focus on the molecules: CheA, CheB, CheR, CheW, CheY, and CheZ. Attractants and repellents are bound to specific transmembrane receptors (chemoreceptors) (on the left hand side of Figure 8) which are coupled with a scaffolding protein (CheW) and a histidine kinase (CheA) to form complexes within the cell. CheA phosphorylates itself modifying the rate at which a messenger protein (CheY) is

phosphorylated. The phosphorylated form of CheY (CheYp) modulates the flagella bundle's tumble probability. Binding of attractants to receptors decreases the rate of CheA phosphorylation, which decreases phosphorylation of CheY, resulting in a lower probability of tumbling, explaining why higher concentrations of attractants produce longer runs. The pathway adapts to high and low concentrations so that the chemotaxis behaviour is solely dependent on temporal changes in concentrations, independent of magnitude.

Adaption to a concentration's magnitude occurs via methylation of the chemoreceptors controlled by CheBp which demethylates the receptor and CheR which methylates the receptor. CheAp inversely promotes the phosphorylation of CheB. In low concentrations of attractant and high concentrations of repellent the amount of CheAp is high resulting in less CheB phosphorylation thus less demethylation of the receptor. This increases the methylation effect of CheR, which increases the amount of CheA phosphorylation, which increases the phosphorylation of CheY. Thus, in lower concentrations of attractant the tumble probability increases. CheY is dephosphorylated rapidly by CheZ. For more details see [2, 5].

We use a simplified version of this pathway where methylation through CheR is removed by using only CheB to directly affect adaption. Because the receptor models are extremely simple without adaption through methylation, the methylation of receptors must be approximated within a single reaction which mediates the phosphorylation of CheA. Thus, the adaption process is simplified in our model to allow it to be more easily expressed in a single reaction. The implication of this simplification is that adaption is faster acting and has a greater effect as it is not mediated through a fine balance of methylation by CheR and demethylation by CheBp. Additionally, we eliminate the scaffold molecule CheW, due to the simplified receptors, and the promoter of CheY dephosphorylation, CheZ, as it is a constant that can be expressed in the reaction. These pathway simplifications fit our simplified receptor model giving a smaller model that is quicker to simulate than a full adaption process.

Figure 9 shows the chemotaxis pathway defined in μ Cell. Reaction rates are defined in μ Cell in *mass action* form. For the chemotaxis pathway the reactions are:



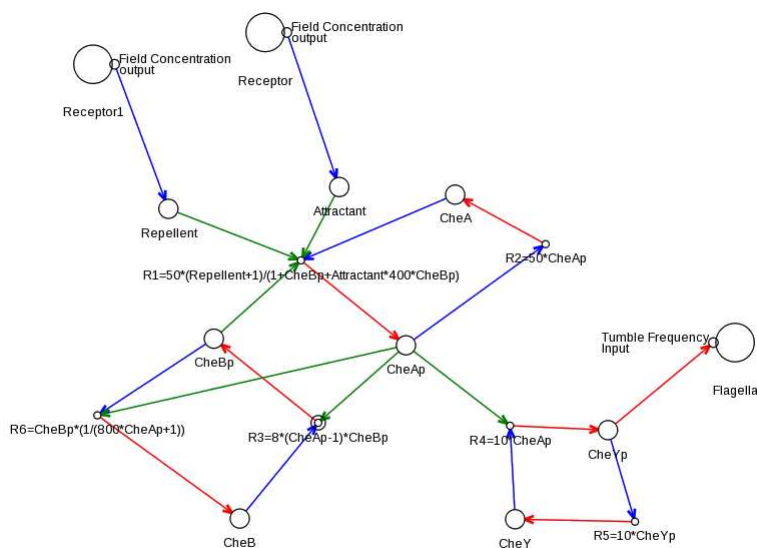


Figure 9: The chemotaxis pathway in the μ Cell cell definition editor.

2.2.4 Modelling Flagella

As described above, the tumble probability of a cell is controlled by the effects of the phosphorylated CheY molecule on the flagella bundle. Figure 10 informally describes the procedural model of the flagella bundle. The flagella bundle model consists of two alternating states: running and tumbling. Each state has a duration of time spent performing the action of that state. The tumble duration is determined by the maximum tumble duration specified in the flagella parameters minus a random scaling, between 0 and 0.5, of the maximum tumble duration. During tumbling, the cell re-orient itself randomly. The *run* duration is a multiple of the reciprocal of the *tumble update frequency*, i.e. *tumble update time* (specified in the cell definition editor), which acts as a minimal unit of running time. The concentration of CheYp is tested in each iteration of the *run* state and changes the likelihood of switching back to *tumble*. When CheYp is high the likelihood of switching is high (0.9), when it is low the likelihood of switching is low (0.1). During a *run* the cell is propelled forwards in the current orientation.

This model is hard-coded in C# into μ Cell. In the future, we hope to provide an abstract procedural modelling language for modifying and defining new components (see *Further Work*).

2.3 Chemotaxis Experiment

In order to test whether μ Cell was able to capture the link between models for flagella and receptors and a known signalling pathway controlling

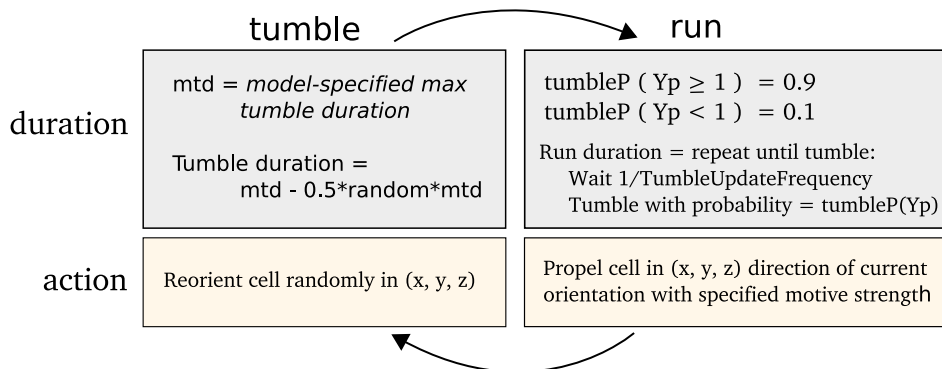


Figure 10: Informal description of the tumble and run behaviours in the flagella bundle model.

chemotaxis, we carried out simulated experiments testing the operation of the models.

2.3.1 Experiment 1

The first experiment tests the average run duration of chemotaxis in the presence of an attractant. A chemotaxis-enabled cell was placed in an environment with an attractant concentration gradient; the average run duration was measured and compared with the average run duration for a control cell in an environment where no gradient was present. The tumble durations were also measured, with the understanding that they would be approximately the same in both cases, as, in our model, the tumble duration is independent of the attractant concentration.

The spatial environment of the experiment was a cuboid of size $80 \times 80 \times 80\text{mm}^3$. Into the environment we placed a single cell whose model contained the chemotaxis pathway described previously, a single attractant receptor model, and a flagella bundle model, configured with the default motive strength 0.8, tumble update frequency 0.5, and max tumble duration 2. The cell was placed near the edge of the environment at co-ordinates (-25, 0, 0), 15mm from the boundary and 25mm from the centre of the environment. In the control test there was no attractant present. In the main test, we specified a densely centred sphere of attractant concentrated at the centre of the environment, with radius of 30mm and central concentration of 10.0 micromoles in total – equivalent to injecting a 10.0 micromoles attractant concentration at the centre of the environment and allowing it to evenly diffuse before the start of the experiment up to a radius of 30mm from the centre in each direction. The constant rate of diffusion we used was low, at 0.001.

The experiment was run for 400s with a temporal resolution of 0.05s.

The control test and main test were repeated 5 times each with 5 cells tracked each time. The mean run duration of a cell was measured. The results are shown in Section 3.1.1.

2.3.2 Experiment 2

The second experiment tested whether the average run durations of a cell eventually decrease when a high concentration is reached, thus allowing cells to congregate at the highest concentration of an attractant and remain in the vicinity. The second experiment also tested whether cells actually move up the concentration gradient towards the higher concentration of the attractant.

The spatial setup was the same as the first experiment, although here we used 100 cells uniformly distributed in the spatial environment. In the control test we placed no attractant and in the main test we again added a 30mm radius densely centred sphere concentration gradient of 10 micromoles in total. The constant rate of diffusion used was low at 0.001. The experiment was run for 800s with a resolution of 0.05s and observed 3 times.

The average attractant within the cell population was measured during the experiment, and we hypothesized that it would steadily increase as the cells congregate in the centre, but that the first derivative of the cell population curve would eventually decrease as cells reach the relatively stable region of the high concentration. The results are shown in Section 3.1.3.

3 Results

Described in this section are the results from the two chemotaxis experiments in μ Cell and a brief note on the results of the project in terms of the μ Cell tool and the learning outcomes for the team.

3.1 Chemotaxis Experiment

The general behaviour observed in these simulations matched the experimental behaviour of *E. coli* chemotaxis reported in the literature.

3.1.1 Experiment 1

The results for the first experiment are tabulated in Figure 11. When cells were placed in the environment with an increasing concentration gradient towards the centre, the mean run duration increased to just over twice that of the control group with no attractant present. This matches the expected behaviour of cells performing chemotaxis towards an attractant. The mean maximum run duration was much higher in the main experiment than in the control experiment.

As predicted, the mean tumble time was roughly the same (up to 2 decimal places) in the control and the main experiment, with a very slight difference in the mean deviation, as the tumble duration is independent of the attractant concentration. The maximum tumble durations are identical, as they are fixed in the flagella model at 2s as stated in the experiment method (the 0.05 extra represents one extra time step that can elapse before switching state).

	Control	Main
Concentration (moles $\times 10^{-6}$)	0	10 densely centered sphere
Mean tumble duration (s)	1.52 ± 2.77	1.52 ± 2.73
Mean run duration (s)	2.25 ± 6.25	4.55 ± 0.42
Max run duration (s)	5.82 ± 1.10	29.68 ± 6.76
Max tumble duration (s)	2.05 ± 1.33	2.05 ± 1.33

Figure 11: Experiment 1 results (to 2 decimal places) \pm mean deviation

3.1.2 Comparing Results of Experiment 1 to Real Experimental Data

We compared the results from experiment 1 with real-world experimental data for chemotaxis of an *E. coli* “wild type” of in a capillary tube with a concentration gradient of 10 micromoles of serine from [14]:

	Control	Gradient
Concentration (moles $\times 10^{-6}$)	0	10
Mean run duration (s)	0.83 ± 0.88	1.67 ± 2.56

Although these real-world measurements differ from our simulation results, both exhibit the same behaviour of run duration roughly doubling in the presence of a gradient. In fact, we can use experimental data such as this to adjust the model parameters. In this case, the tumble update frequency can be scaled according to the magnitude difference between the μ Cell results and the real-world results. Using a tumble update frequency of 1.355 instead of the previous 0.5, μ Cell measures the following:

	Control	Gradient
Concentration (moles $\times 10^{-6}$)	0	10
Mean run duration (s)	0.83 ± 1.44	1.74 ± 0.33

Note, however that the average deviation is very different between the experimental data and the data collected from μ Cell. We conjecture that this is a result of the approximated adaption pathway in our pathway model for chemotaxis. The approximated adaption pathway results in overly quick

adaption to the magnitude of the relevant concentration. Therefore, the mean deviation of a cell's tumble duration when in a gradient is lower than expected as the pathway adapts more quickly to a higher concentration, thus less deviation occurs. The probability weightings of the flagella model may also require further tuning. Further collaboration with biologists would be needed to tune the models based on results from real-world, *in vivo* experiments.

3.1.3 Experiment 2

Figure 12 shows that in our simulation the mean attractant over all cells, in all three experiments, increased in the presence of a concentration gradient and the first derivative of the curve decreased as the cells reached the area of greatest nutrient concentration. The curve is irregular at its limit due to tumbling and short runs resulting in occasional forays into areas of slightly lower concentration.

Figure 13 shows one set of visual results from the 3D spatial environment for the first 400 seconds of the simulated time. In the control situation (Figure 13(b)), the cells wander randomly with no attractant to promote directed movement. Conversely, in the presence of a concentration gradient (Figure 13(a)) almost all the cells converge in the high concentration area in the environment's centre. There are a few cells that have not reached the centre due to the fact that chemotaxis, even though it is a biased walk, is a random walk and can therefore be unsuccessful for a long time.

4 Related Work

There are numerous tools that provide modelling and cell design abilities and/or simulation features to aid research in biology. A few projects that share some commonality with μ Cell will be discussed here.

The modelling and simulation of signalling pathways can be performed with many existing tools; the SBML website provides an extensive list of software supporting SBML models³. μ Cell does not claim to improve upon these tools in terms of speed of simulation or SBML-support but is novel, as far the authors are aware, in providing a tool for combining pathway models with pre-defined models of cell components for the simulation of spatial behaviour.

Virtual Cell, an advanced tool for cell simulations based on layers of models, performs complex spatial simulations of compartments and membranes within a single cell derived from real geometric data [13]. The spatial simulations within a cell in Virtual Cell are at a finer granularity than μ Cell's spatial simulations at the multi-cellular level. Virtual Cell provides

³<http://sbml.org/SBML-Software-Guide/SBML-Software-Summary>

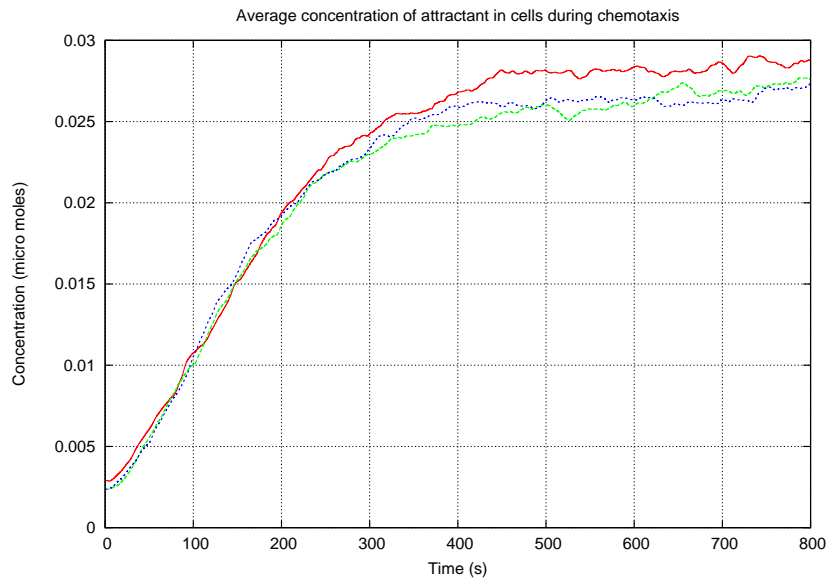


Figure 12: Mean attractant across all cells increased as they moved up the concentration gradient, eventually reaching a plateau as the cells converge at the area of highest concentration.

some similar features to μ Cell, such as the simulation of diffusion of concentrations, although Virtual Cell employs more advanced fluid dynamics techniques. Virtual Cell uses a system for compiling user formulae into code for simulation, similar to our own approach of folding abstract syntax trees for formulae into functions.

The BioSPICE open source framework for modelling and simulation in systems biology is an extendable framework with a multitude of pluggable modules that can be configured to interoperate [11]. Systems Biology Workbench (SBW) is a grand effort to combine the best tools from all aspects of biological modelling into a single complete framework to enable interoperation between tools via standardisation [7]. The SBML standard is at the heart of this endeavour, originally introduced by the same organisation. BioSPICE and SBW are both formidable systems that are at times difficult to use, with a high barrier of entry for inexperienced users. μ Cell is more specific and succinct in its purposes and features, although the spirit of interoperation is shared at a smaller scale of model interoperation.

Another approach to modelling and simulation of spatial behaviours is through the programming of custom models, either through generalised modelling tools or programming languages. For example, NetLogo [17] provides a generalised programmable modelling environment into which μ Cell-like models and simulations could be programmed. Other spatial models have been implemented using custom programming languages, such as the

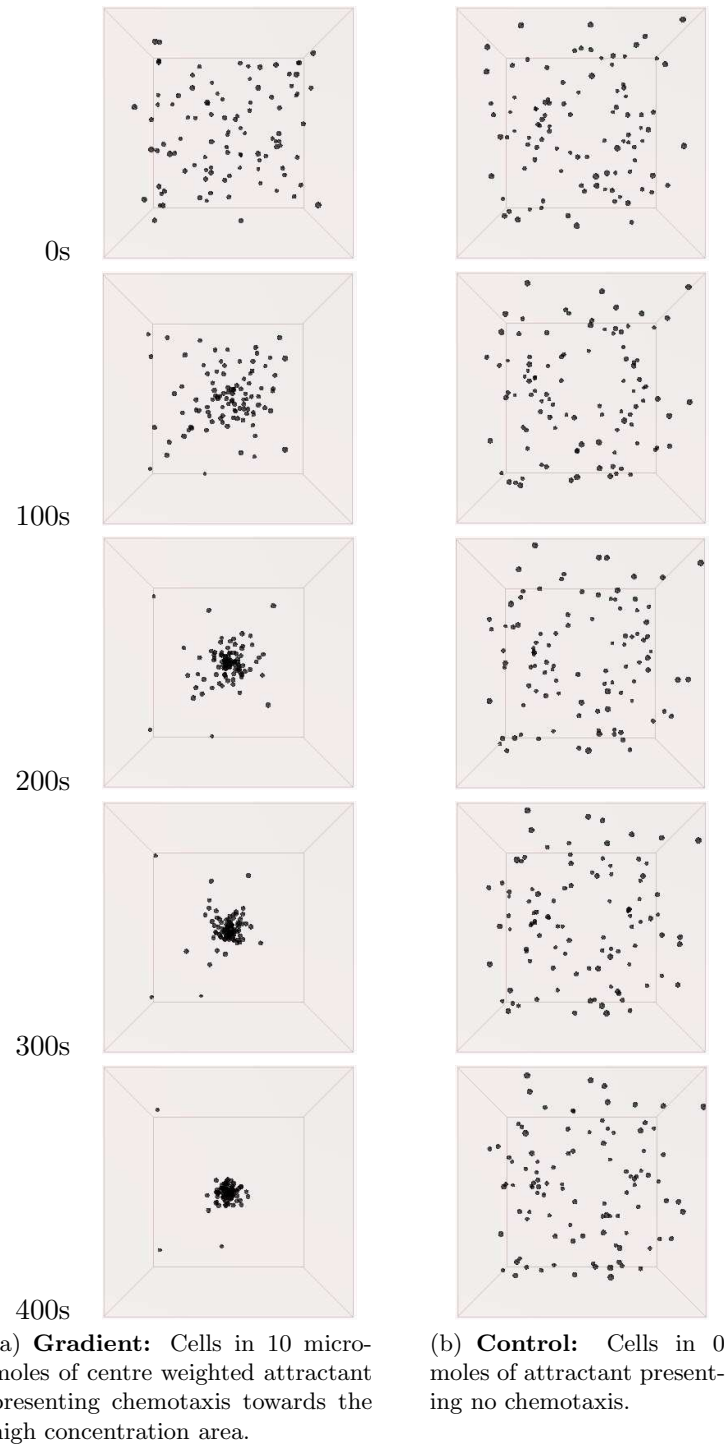


Figure 13: Screen captures of the 3D spatial environment shown from the front during simulation at approximately 100 second intervals.

simulation of aggregation in *Dictyostelium* molds using a specially developed “cell” programming language [1]. μ Cell provides specialised modelling and simulation tools for emerging behaviours of cells without requiring any programming experience from the user.

The CompuCell3D modelling environment provides 2D and 3D visualisations of various cell models [4], including cellular Potts model simulations of morphogenesis – the shaping of cells. CompuCell3D is also capable of simulating other processes such as clustering, cell death, cell haptotaxis (directional growth of cells), and chemotaxis. CompuCell3D uses custom modules written in C++ and Python, requiring programming expertise from the user and custom rules bases to produce models and simulations, as opposed to providing pre-defined models and using lower-level biochemical dynamics to drive these processes as in μ Cell.

Spatial behaviours have been modelled and simulated using statistical models, such as extended Potts models [6], whose behaviours are not mediated by signalling pathways as in μ Cell.

5 Further Work

There is a considerable amount of potential further work. A more extensive list with outlined research proposals for student projects, is available on the μ Cell Wiki⁴. We discuss a few areas of work briefly.

Currently, the numerical accuracy of measurements within μ Cell is correct up to the definition of the models, but measurements taken from simulations may not match measurements from *in vivo* experiments. As suggested in Section 3.1.2, the parameters of models can be tweaked to give data that matches experimental data to an extent, but further collaboration with biologists is required if more realistic measurements are to be achieved. An example usage of μ Cell in research may be the modification of a signalling pathway due to a genetic fault and to test the effects of this modification on the emerging behaviours of the cell. For example, in *E. coli* chemotaxis, if CheY can not phosphorylate quickly enough due to some unusual inhibition relation, will chemotaxis occur?

Currently, there are only procedural models for flagella bundles, receptors, and cell bodies (which facilitate cell collisions). This set should be extended to include components for modelling further processes such as cell growth, death, mitosis and cytokinesis (cell division), haptotaxis, and cell excretion. Furthermore, there should be tools for the user to develop their own procedural models of cell components. This may involve some form of synthetic language, or construction tool, that should be sufficiently flexible to allow definition of current and future models.

⁴<http://github.com/dorchard/mucell/wikis/further-work>

A solution, already applied in existing tools such as CompuCell3D, is to allow modules to be written in a standard programming language that are then compiled and imported into the software. However this requires that users have programming experience, an assumption that should not necessarily be made. This raises the question: can a programming language for cell component models really be tractable for a non-programmer? A visual language, or a language with appropriate abstractions that match biological thinking, could prove a useful avenue of exploration. This is not only a μ Cell specific problem but applies to many areas of interdisciplinary research. How can individuals communicate their ideas and problems to a computer? And even: how do individuals interoperate and communicate given different levels of expertise?

6 Conclusions

This paper has introduced the μ Cell software tool for modelling and simulation of multi-cellular environments with a particular focus on the spatial behaviour of cells. The spatial behaviour of cells can be modelled in μ Cell via the interoperation of signalling pathway models (defined in the SBML data format) with pre-defined procedural models of cell components, such as flagella bundles. Thus spatial behaviours are controlled by a cell's signalling pathway. This approach to spatial simulations differs from stochastic approaches or cellular automata based approaches. The capabilities of this tool were demonstrated with two experiments showing μ Cell's ability to model and simulate *E. coli* chemotaxis. A user of μ Cell is not required to do any programming of their own as the procedural models of cell components are built-in and configurable.

The μ Cell tool developed during the project was successful in its goal to be practical and usable for modelling and simulation of cell behaviour in spatial environments. The tool is (we hope) easy to use and may also be useful as a teaching tool in biology. The tool is now freely available as open-source software and has a public code repository and Wiki⁵. A video is available showing μ Cell being used in a chemotaxis experiment⁶. Development of the tool has continued, albeit slowly, since the formal end of the project, and we expect to collaborate further with biologists to improve its usefulness.

Acknowledgements

Many thanks are due to David Whitworth for all his help during the project. Thank you to all the biologists and biochemists who endured our many questions. Thanks also to the helpful comments of the anonymous referees.

⁵<http://github.com/dorchard/mucell/wikis>

⁶<http://github.com/dorchard/mucell/wikis/screenshots-and-videos>

References

- [1] Pankaj Agarwal. Simulation of aggregation in Dictyostelium using the cell programming language. In *Computer Applications in the Biosciences*, volume 6, pages 647–655, 1994.
- [2] U Alon, MG Surette, N Barkai, and S Leibler. Robustness in bacterial chemotaxis. *Nature*, 397(6715):168–171, January 1999.
- [3] Howard C. Berg and Douglas A. Brown. Chemotaxis in Escherichia coli Analysed by Three-dimensional Tracking. *Nature*, 239(5374):500–504, October 1972.
- [4] Trevor M. Cickovski, Chengbang Huang, Rajiv Chaturvedi, Tilmann Glimm, H. George E. Hentschel, Mark S. Alber, James A. Glazier, Stuart A. Newman, and Jesus A. Izaguirre. Compucell3d. *IEEE/ACM Transactions on Computational Biology and Bioinformatics (TCBB)*, 2:273–288, 2005.
- [5] Joseph J. Falke, Randal B. Bass, Scott L. Butler, Stephen A. Chervitz, and Mark A. Danielson. THE TWO-COMPONENT SIGNALING PATHWAY OF BACTERIAL CHEMOTAXIS: A Molecular View of Signal Transduction by Receptors, Kinases, and Adaptation Enzymes. *Annual Review of Cell and Developmental Biology*, 13:457–512, November 1997.
- [6] Garner François and James Glazier. Simulation of biological cell sorting using a two-dimensional extended Potts model. *Physical Review Letters*, 69(13):2013–2016, September 1992.
- [7] M. Hucka, A. Finney, H. Sauro, and H. Bolouri. Introduction to the Systems Biology Workbench. *JST ERATO Kitano Symbiotic Systems Project*, May 2001.
- [8] M. Hucka, A. Finney, H. M. Sauro, H. Bolouri, J. C. Doyle, and H. et. al Kitano. The systems biology markup language (SBML): a medium for representation and exchange of biochemical network models. *Bioinformatics*, 19(4):524–531, 2003.
- [9] Minoru Kanehisa and Susumu Goto. KEGG: Kyoto Encyclopedia of Genes and Genomes. *Nucl. Acids Res.*, 28(1):27–30, 2000.
- [10] KEGG. Bacterial Chemotaxis Escherichia coli K-12 MG1655, Retrieved December 2008. http://www.genome.jp/dbget-bin/show_pathway?eco02030.

- [11] S. P. Kumar and J. C. Feidler. BioSPICE: a computational infrastructure for integrative biology. *OMICS: A Journal of Integrative Biology*, 7(3):223–225, September 2003.
- [12] R M MacNab. Flagella and motility. In *Escherichia coli and Salmonella: Cellular and Molecular Biology*, pages 123–145, 1996.
- [13] I.I. Moraru, J.C. Schaff, B.M. Slepchenko, M.L. Blinov, F. Morgan, A. Lakshminarayana, F. Gao, Y. Li, and L.M. Loew. Virtual cell modelling and simulation software environment. *Systems Biology, IET*, 2(5):352–362, September 2008.
- [14] Igor Rojdestvenski. Metabolic pathways in three dimensions. *Bioinformatics*, 19(18):2436–2441, 2003.
- [15] Victor Sourjij. Receptor clustering and signal processing in E. coli chemotaxis. *TRENDS in Microbiology*, 12, December 2004.
- [16] Y Sowa and R M Berry. Bacterial flagellar motor. *Quarterly reviews of biophysics*, (2):103–132, 2008.
- [17] Seth Tisue and Uri Wilensky. NetLogo: A simple environment for modeling complexity. In *International Conference on Complex Systems*, pages 16–21, 2004.

A Interpolation using Gaussian Weighting

The discretisation of the continuous simulation environment into cubes produces discontinuous changes in concentration between cubes and a constant concentration inside a cube. Chemotaxis relies on continuous changes in the concentration gradient thus the discontinuity and quiescence poses a significant problem for the chemotaxis simulation. The problem is overcome by interpolation using Gaussian weighting.

A co-ordinate (x, y, z) in the simulation environment has a mapping to a cube with co-ordinates (i, j, k) in the approximated concentration space. Each cube has 26 neighbours that are connected either by an edge, face, or vertex. The 27 cubes surrounding (i, j, k) , including itself, are sampled, taking a weighted average of each where the weighting is based on the distance from the (x, y, z) to the centroid of each cube (illustrated in Figure 14 with 5 cubes as opposed to 27). A Gaussian function is applied to each distance to provide smooth interpolation:

$$f(P) = \sum_{i=1}^{27} \left(\frac{e^{-\frac{d_i}{c_L}}}{\sum_{i=1}^{27} e^{-\frac{d_i}{c_L}}} \right) \times q_i \quad (3)$$

Where d_i is the distance from the point P to the centre of the i^{th} cube centre in the array of $3 \times 3 \times 3$ cubes surrounding point P , q_i is the quantity in the i^{th} cube, and finally c_L is the length of the cube's side. Note that in general:

$$\sum_{n=0}^i \left(\frac{f(n)}{\sum_{n=0}^i f(n)} \right) = \frac{\sum_{n=0}^i f(n)}{\sum_{n=0}^i f(n)} = 1 \quad (4)$$

Hence the weighting kernel will always sum to 1. For performance reasons the nested summation is computed separately in an initial pass of the 27 cubes, stored, and then used in a second pass to avoid nested computation.

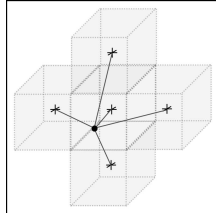


Figure 14: Nutrient field sampling interpolation scheme